

ORBITAL GRAVITATION AND ORBITAL HAUSDORFF STABILITY OF LOTKA-VOLTERRA MODEL

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Abstract

The main object of investigation in the present paper is the classical Lotka-Volterra mathematical model. There are introduced orbital gravitation and orbital Hausdorff stability of the trajectories of this model. Under natural assumptions, it is showed that Lotka-Volterra model possesses these properties.

Key words: model of Lotka-Volterra, trajectory, orbital gravitation, orbital Hausdorff stability.

1. Introduction

The Lotka-Volterra mathematical model describes quite accurately the evolution dynamics of predator-prey interactions of an isolated (without external influences) biosystem. The classical initial problem of this model has a form:

$$\begin{aligned} (1) \quad & \frac{dm}{dt} = \dot{m} = F_m(m, M) = m(r_1 - q_1 M), \\ (2) \quad & \frac{dM}{dt} = \dot{M} = F_M(m, M) = -M(r_2 - q_2 m), \\ (3) \quad & m(0) = m_0; \quad M(0) = M_0, \end{aligned}$$

Where:

- $m = m(t) > 0$ and $M = M(t) > 0$ are the quantities of biomasses of the prey and the predator respectively at the moment $t \geq 0$;
- The constants $r_1 > 0$ and $r_2 > 0$ are specific coefficients of the relative growth of the first species (prey) and the second species (predator), respectively;
- The constants $q_1 > 0$ and $q_2 > 0$ are the coefficients reflecting interspecies competition for the prey and the predator, respectively;
- The constants $m_0 > 0$ and $M_0 > 0$ are the quantities of biomasses of both species at the initial moment $t = 0$.

It is known that the system (1), (2) possesses:

- Unstable stationary point $(0, 0)$, (the origin is a saddle point);
- Stable stationary point $(m_{00}, M_{00}) = \left(\frac{r_2}{q_2}, \frac{r_1}{q_1} \right)$;
- A first integral of the following form

$$\begin{aligned} U(m, M) &= q_1 M + q_2 m - r_1 \ln M - r_2 \ln m + r_1 \left(\ln \frac{r_1}{q_1} - 1 \right) + r_2 \left(\ln \frac{r_2}{q_2} - 1 \right) \\ &= W(m, M) - W(m_{00}, M_{00}), \end{aligned}$$

where

$$W(m, M) = q_1 M + q_2 m - r_1 \ln M - r_2 \ln m;$$

- For any point $(m, M) \in \square^+ \times \square^+$, $(m, M) \neq (m_{00}, M_{00})$ the inequality $U(m, M) > 0$ is valid. It is fulfilled $U(m_{00}, M_{00}) = 0$;
- For any constant $c \geq 0$ the implicitly given curve

$$\gamma_c = \{(m, M) : U(m, M) = c\}$$

is a trajectory of the system (1), (2) with a properly chosen initial condition (it is sufficient to assume that $U(m_0, M_0) = c$);

- For any constant $c > 0$ the set

$$D_c = \{(m, M) : U(m, M) < c\}$$

is a connected domain, located in $\square^+ \times \square^+$, with a contour $\partial D_c = \gamma_c$;

- For any constant $c > 0$ it is satisfied $(m_{00}, M_{00}) \in D_c$;
- If $0 < c_1 < c_2$, then $\gamma_{c_1} \in D_{c_2}$.

Different aspects of the population dynamics are studied in [1] ÷ [27].

2. Statement of the problem and preliminary remarks

If the points $a(a_1, a_2, \dots, a_n)$, $b(b_1, b_2, \dots, b_n) \in \square^n$, then their dot product, the Euclidean norm and the Euclidean distance between them are denoted respectively by:

$$\begin{aligned} \langle a, b \rangle &= a_1 b_1 + a_2 b_2 + \dots + a_n b_n, \\ \|a\| &= \langle a, a \rangle^{1/2} = \sqrt{a_1^2 + a_2^2 + \dots + a_n^2}, \\ \rho_E(a, b) &= \sqrt{(a_1 - b_1)^2 + (a_2 - b_2)^2 + \dots + (a_n - b_n)^2}. \end{aligned}$$

It is clear that equality $\|a - b\| = \rho_E(a, b)$ is valid. If the non empty sets $A, B \subset \square^n$, then the Euclidean and the Hausdorff distances between them are denoted respectively by:

$$\begin{aligned} \rho_E(A, B) &= \inf \left\{ \inf \left\{ \rho_E(a, b), a \in A, b \in B \right\} \right\}, \\ \rho_H(A, B) &= \max \left\{ \sup \left\{ \inf \left\{ \rho_E(a, b), a \in A, b \in B \right\} \right\}, \sup \left\{ \inf \left\{ \rho_E(a, b), b \in B, a \in A \right\} \right\} \right\}. \end{aligned}$$

The inequality $\rho_E(A, B) \leq \rho_H(A, B)$ is obviously true.

The Euclidean and the Hausdorff distance between the trajectories γ_{c_0} and $\gamma_{c_0^*}$ satisfy the following equalities respectively:

$$\begin{aligned} \rho_E(\gamma_{c_0^*}, \gamma_{c_0}) &= \inf \left\{ \inf \left\{ \rho_E((m^*, M^*), (m, M)), (m^*, M^*) \in \gamma_{c_0^*}, (m, M) \in \gamma_{c_0} \right\} \right\}, \\ \rho_H(\gamma_{c_0^*}, \gamma_{c_0}) &= \max \left\{ \sup \left\{ \inf \left\{ \rho_E((m^*, M^*), (m, M)), (m^*, M^*) \in \gamma_{c_0^*}, (m, M) \in \gamma_{c_0} \right\} \right\}, \right. \\ &\quad \left. \sup \left\{ \inf \left\{ \rho_E((m^*, M^*), (m, M)), (m, M) \in \gamma_{c_0}, (m^*, M^*) \in \gamma_{c_0^*} \right\} \right\} \right\}. \end{aligned}$$

Definition 1. We say that the system (1), (2) is orbital gravitating in the domain D with a constant $\kappa \geq 1$, if:

$$\begin{aligned} & (\forall c_0^*, c_0 \in \square^+): (\gamma_{c_0^*}, \gamma_{c_0} \in D) \Rightarrow \rho_H(\gamma_{c_0^*}, \gamma_{c_0}) \leq \kappa \cdot \rho_E(\gamma_{c_0^*}, \gamma_{c_0}) \\ \Leftrightarrow & \max \left\{ \sup \left\{ \inf \left\{ \rho_E \left((m^*, M^*), (m, M) \right), (m^*, M^*) \in \gamma_{c_0^*}, (m, M) \in \gamma_{c_0} \right\}, \right. \right. \\ & \left. \left. \sup \left\{ \inf \left\{ \rho_E \left((m^*, M^*), (m, M) \right), (m, M) \in \gamma_{c_0} \right\}, (m^*, M^*) \in \gamma_{c_0^*} \right\} \right\} \right\} \\ & \leq \kappa \cdot \inf \left\{ \inf \left\{ \rho_E \left((m^*, M^*), (m, M) \right), (m^*, M^*) \in \gamma_{c_0^*}, (m, M) \in \gamma_{c_0} \right\} \right\}. \end{aligned}$$

Definition 2. We say that the solution of problem (1), (2), (3) is orbital Hausdorff stable if:

$$\begin{aligned} & (\forall \varepsilon > 0) (\forall (m_0, M_0) \in \square^+ \times \square^+) (\exists \delta = \delta(\varepsilon, m_0, M_0) > 0): \\ & (\forall (m_0^*, M_0^*) \in \square^+ \times \square^+, \rho_E((m_0^*, M_0^*), (m_0, M_0)) < \delta) \Rightarrow \rho_H(\gamma_{c_0^*}, \gamma_{c_0}) < \varepsilon, \end{aligned}$$

where $c_0 = U(m_0, M_0)$ and $c_0^* = U(m_0^*, M_0^*)$.

The following two theorems are auxiliary.

Theorem 1. Assume that:

1. The constants c_0 and c_0^* satisfy the inequalities $0 < c_0 < c_0^*$;
2. The domain $D = D_{c_0^*} \setminus D_{c_0}$.

Then for every point $(m, M) \in \gamma_{c_0}$ there exists a point $(m^*, M^*) \in \gamma_{c_0^*}$ such that the segment

$$\mu = \left\{ (m_\mu, M_\mu); m_\mu = (1-\lambda)m + \lambda m^*, M_\mu = (1-\lambda)M + \lambda M^*, 0 \leq \lambda \leq 1 \right\} \subset \overline{D}.$$

Proof. Let the point $(m, M) \in \gamma_{c_0}$. We consider the half-line

$$sl = \left\{ (m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00})), \lambda' \geq 0 \right\}.$$

There exists a constant $\lambda^* > 0$ such that

$$(m + \lambda^*(m - m_{00}), M + \lambda^*(M - M_{00})) = (m^*, M^*) \in \gamma_{c_0^*}.$$

It is true that

$$\begin{aligned} \mu &= \left\{ ((1-\lambda)m + \lambda m^*, (1-\lambda)M + \lambda M^*), 0 \leq \lambda \leq 1 \right\} \\ &= \left\{ (m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00})), 0 \leq \lambda' \leq \lambda^* \right\}, \end{aligned}$$

where $\lambda = \lambda' / \lambda^*$. We shall show that $\mu \in \overline{D}$.

One of the following cases is valid:

1. $m \leq m_{00}, M \leq M_{00}$;
2. $m < m_{00}, M > M_{00}$;
3. $m > m_{00}, M < M_{00}$;
4. $m \geq m_{00}, M \geq M_{00}$,

where $m_{00} = r_2/q_2$ and $M_{00} = r_1/q_1$. We shall consider only case 1. In this case we get:

$$q_2 - \frac{r_2}{m} \leq q_2 - \frac{r_2}{m_{00}} = q_2 - \frac{r_2}{r_2/q_2} = 0, \quad q_1 - \frac{r_1}{M} \leq q_1 - \frac{r_1}{M_{00}} = q_1 - \frac{r_1}{r_1/q_1} = 0.$$

Let the function $F(\lambda') = U((m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00})))$, $0 \leq \lambda' \leq \lambda^*$. We have

$$\begin{aligned} \frac{d}{d\lambda'} F(\lambda') &= \frac{d}{d\lambda'} U((m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00}))) \\ &= \frac{d}{d\lambda'} W((m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00}))) \\ &= \left(q_2 - \frac{r_2}{m + \lambda'(m - m_{00})} \right) (m - m_{00}) + \left(q_1 - \frac{r_1}{M + \lambda'(M - M_{00})} \right) (M - M_{00}) \geq 0, \end{aligned}$$

because

$$\begin{aligned} m - m_{00} \leq 0, \quad q_2 - \frac{r_2}{m + \lambda'(m - m_{00})} \leq q_2 - \frac{r_2}{m} \leq 0, \\ M - M_{00} \leq 0, \quad q_1 - \frac{r_1}{M + \lambda'(M - M_{00})} \leq q_1 - \frac{r_1}{M} \leq 0. \end{aligned}$$

Therefore, $F(0) \leq F(\lambda') \leq F(\lambda^*)$, i.e.

$$\begin{aligned} c_0 = U(m, M) = F(0) &\leq F(\lambda') \\ &= U((m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00}))) \\ &\leq F(\lambda^*) = U(m^*, M^*) = c_0^*, \quad 0 \leq \lambda' \leq \lambda^*. \end{aligned}$$

From last inequalities we conclude that $((m + \lambda'(m - m_{00}), M + \lambda'(M - M_{00}))) \in \bar{D}$, $0 \leq \lambda' \leq \lambda^*$ or $\mu \in \bar{D}$.

The theorem is proved.

Theorem 2. Assume that:

1. The constants c_0 and c_0^* satisfy the inequalities $0 < c_0 < c_0^*$;
2. The connected set $\gamma \subset D = D_{c_0^*} \setminus D_{c_0}$;
3. For every points $(m, M) \in \gamma_{c_0}$ and $(m^*, M^*) \in \gamma_{c_0^*}$ the segment

$$\mu = \left\{ (m_\mu, M_\mu); m_\mu = (1 - \lambda)m + \lambda m^*, M_\mu = (1 - \lambda)M + \lambda M^*, 0 \leq \lambda \leq 1 \right\}$$

intersects the set γ , i.e. $\gamma \cap \mu \neq \emptyset$.

Then for every point $(m, M) \in \gamma_{c_0}$ there exist the points $(m^*, M^*) \in \gamma_{c_0^*}$ and $(m', M') \in \gamma \cap \mu$ such that the vector $(m^* - m, M^* - M)$ is collinear with $\text{grad}U(m', M')$.

Proof. Let the point $(m, M) \in \gamma_{c_0}$. Similarly of the proof of previous theorem one of the following cases is valid:

1. $m \leq m_{00}, M \leq M_{00}$;
2. $m < m_{00}, M > M_{00}$;
3. $m > m_{00}, M < M_{00}$;
4. $m \geq m_{00}, M \geq M_{00}$.

Case 1. $m \leq m_{00}, M \leq M_{00}$. We denote:

$$\begin{aligned} \gamma'_{c_0^*} &= \gamma_{c_0^*} \cap \{(m^*, M^*), m^* \leq m, M^* \leq M\}, \\ \gamma' &= \gamma \cap \{(m', M'), m' \leq m, M' \leq M\}. \end{aligned}$$

For each point $(m', M') \in \gamma'$ there are satisfied:

$$\begin{aligned} \text{grad}U(m', M') &= \left(\frac{\partial U(m', M')}{\partial m}, \frac{\partial U(m', M')}{\partial M} \right) = \left(q_2 - \frac{r_2}{m'}, q_1 - \frac{r_1}{M'} \right), \\ q_2 - \frac{r_2}{m'} &\leq q_2 - \frac{r_2}{m} \leq q_2 - \frac{r_2}{m_{00}} = q_2 - \frac{r_2}{r_2/q_2} = 0, \quad q_1 - \frac{r_1}{M'} \leq 0. \end{aligned}$$

Case 1.1. Let $m < m_{00}$ and $M < M_{00}$. Then the following strict inequalities are valid:

$$q_2 - \frac{r_2}{m'} < 0, \quad q_1 - \frac{r_1}{M'} < 0.$$

Let μ is the segment with the endpoints $(m, M) \in \gamma_{c_0}$ and $(m^*, M^*) \in \gamma_{c_0^*}$. For every point $(m^*, M^*, m', M') \in \gamma'_{c_0^*} \times (\gamma' \cap \mu)$ we consider the function

$$F(m^*, M^*, m', M') = \frac{m^* - m}{q_2 - \frac{r_2}{m'}} - \frac{M^* - M}{q_1 - \frac{r_1}{M'}},$$

First, let the point $(m_1^*, M_1^*) = (m, M) \in \gamma'_{c_0^*}$. Then, it is clear that $M_1^* < M$ and therefore

$$F(m_1^*, M_1^*, m', M') = \frac{m - m}{q_2 - \frac{r_2}{m'}} - \frac{M_1^* - M}{q_1 - \frac{r_1}{M'}} < 0.$$

Second, if the point $(m_2^*, M_2^*) = (m^*, M) \in \gamma'_{c_0^*}$, then $m_2^* < m$. We get

$$F(m_2^*, M_2^*, m', M') = \frac{m_2^* - m}{q_2 - \frac{r_2}{m'}} - \frac{M - M}{q_1 - \frac{r_1}{M'}} > 0.$$

Since the function F is continuous on the connected set $\gamma'_{c_0^*} \times (\gamma' \cap \mu)$ then there exists a point (m^*, M^*, m', M') from this set such that

$$F(m^*, M^*, m', M') = 0 \Leftrightarrow \frac{m^* - m}{q_2 - \frac{r_2}{m'}} = \frac{M^* - M}{q_1 - \frac{r_1}{M'}}.$$

This proves the theorem in case 1.1.

Case 1.2. Let $m = m_{00}$ and $M \leq M_{00}$. We assume that $m^* = m$. Then the following equalities are valid:

$$m^* = m = m_{00} = m', \quad q_2 - \frac{r_2}{m'} = 0.$$

and consequently

$$\begin{aligned} (m^* - m, M^* - M) &= (0, M^* - M), \\ \text{grad}U(m', M') &= \left(0, q_1 - \frac{r_1}{M'}\right). \end{aligned}$$

From the last equalities it follows that the vectors $(m^* - m, M^* - M)$ and $\text{grad}U(m', M')$ are collinear.

Case 1.3. Let $m \leq m_{00}$ and $M = M_{00}$. Then, as the previous case we determine

$$\begin{aligned} (m^* - m, M^* - M) &= (m^* - m, 0), \\ \text{grad}U(m', M') &= \left(q_2 - \frac{r_2}{m'}, 0\right). \end{aligned}$$

Therefore, the above vectors are collinear. Under this assumption the theorem is proved.

The remaining three cases: $m < m_{00}, M > M_{00}$; $m > m_{00}, M < M_{00}$ and $m \geq m_{00}, M \geq M_{00}$ are considered similarly so we omit them.

The theorem is proved.

3. Main result

Theorem 3. Assume that:

1. The constants c_1 and c_2 satisfy the inequalities $0 < c_1 < c_2$;
2. The domain $D = D_{c_2} \setminus D_{c_1}$.

Then the system (1), (2) is orbital gravitating in the domain D with a constant

$$\kappa = \frac{\sup \left\{ \|\text{grad}U(m', M')\|, (m', M') \in D \right\}}{\inf \left\{ \|\text{grad}U(m', M')\|, (m', M') \in D \right\}}.$$

Proof. Let the trajectories $\gamma_{c_0}, \gamma_{c_0^*} \subset D$. We have $c_1 < c_0 < c_2$, $c_1 < c_0^* < c_2$ and

$$\begin{aligned} \gamma_{c_0} &= \left\{ (m, M) : U(m, M) = c_0 \right\} \\ &= \left\{ (m, M) : q_1 M + q_2 m - r_1 \ln M - r_2 \ln m + r_1 \left(\ln \frac{r_1}{q_1} - 1 \right) + r_2 \left(\ln \frac{r_2}{q_2} - 1 \right) = c_0 \right\}, \\ \gamma_{c_0^*} &= \left\{ (m, M) : q_1 M + q_2 m - r_1 \ln M - r_2 \ln m + r_1 \left(\ln \frac{r_1}{q_1} - 1 \right) + r_2 \left(\ln \frac{r_2}{q_2} - 1 \right) = c_0^* \right\}. \end{aligned}$$

We assume that $c_0 < c_0^*$. The proof of the case $c_0 > c_0^*$ is similar. The case $c_0 = c_0^*$ is trivial.

Let the point $(m, M) \in \gamma_{c_0}$. Let (m^*, M^*) be a point such that $(m^*, M^*) \in \gamma_{c_0^*}$ and the segment μ with the endpoints (m, M) and (m^*, M^*) belongs to $\overline{D_{c_0^*} \setminus D_{c_0}}$ (see Theorem 1). We consider a function

$$F(\lambda) = U\left(m + \lambda(m^* - m), M + \lambda(M^* - M)\right), \quad \lambda \in [0, 1].$$

We have: $F(0) = U(m, M) = c_0$, $F(1) = U(m^*, M^*) = c_0^*$ and F is continuous differentiable function on the interval $[0, 1]$. Then there exists at last one constant $\lambda_0 = \lambda_0(m, M, m^*, M^*)$, $0 < \lambda_0 < 1$, such that

$$\begin{aligned}
 (4) \quad |c_0^* - c_0| &= |F(1) - F(0)| = |F'(\lambda_0)| \\
 &= \left| \frac{d}{d\lambda} U\left(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)\right) \right| \\
 &= \left| \frac{\partial}{\partial m} U\left(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)\right)(m^* - m) \right. \\
 &\quad \left. + \frac{\partial}{\partial M} U\left(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)\right)(M^* - M) \right| \\
 &= \left| \left\langle \text{grad}U\left(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)\right), (m^* - m, M^* - M) \right\rangle \right| \\
 &= \left| \left\langle \text{grad}U\left(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)\right), \right. \right. \\
 &\quad \left. \left. \left(\frac{m^* - m}{\sqrt{(m^* - m)^2 + (M^* - M)^2}}, \frac{M^* - M}{\sqrt{(m^* - m)^2 + (M^* - M)^2}} \right) \right\rangle \right| \cdot \sqrt{(m^* - m)^2 + (M^* - M)^2}.
 \end{aligned}$$

We denote

$$\begin{aligned}
 \gamma &= \{(m', M') = (m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)), \\
 &\quad \text{where: } (m, M) \in \gamma_{c_0}, (m^*, M^*) \in \gamma_{c_0^*}, \\
 &\quad \left. \left((1 - \lambda)m + \lambda m^*, (1 - \lambda)M + \lambda M^* \right) \in D_{c_0^*} \setminus D_{c_0} \text{ for } 0 < \lambda < 1, |c_0^* - c_0| = |F'(\lambda_0)| \right\}.
 \end{aligned}$$

In other words, the set γ consists of the points (m', M') such that:

- $(m', M') \in \mu$;
- $\mu = \{(m_\mu, M_\mu); m_\mu = (1 - \lambda)m + \lambda m^*, M_\mu = (1 - \lambda)M + \lambda M^*, 0 \leq \lambda \leq 1\}$;
- $(m, M) \in \gamma_{c_0}, (m^*, M^*) \in \gamma_{c_0^*}$;
- $\mu \subset \overline{D_{c_0^*} \setminus D_{c_0}}$;
- $|c_0^* - c_0| = \left| \left\langle \text{grad}U(m', M'), (m^* - m, M^* - M) \right\rangle \right|$.

It is clear that γ is a connected set and for every points $(m, M) \in \gamma_{c_0}$ and $(m^*, M^*) \in \gamma_{c_0^*}$ the segment μ intersects the set γ . According to Theorem 2, it is possible to chose two points $(m^*, M^*) \in \gamma_{c_0^*}$ and $(m', M') = (m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)) \in \gamma \cap \mu$ so that the vector

$$(m^* - m, M^* - M)$$

to be collinear with the vector

$$\text{grad}U(m', M') = \text{grad}U(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)).$$

Then from (4) it follows

$$\begin{aligned} |c_0^* - c_0| &= \left\langle \text{grad}U(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M)), \right. \\ &\quad \left. \frac{\text{grad}U(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M))}{\|\text{grad}U(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M))\|} \right\rangle \cdot \sqrt{(m^* - m)^2 + (M^* - M)^2} \\ &= \|\text{grad}U(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M))\| \cdot \rho_E((m, M), (m^*, M^*)). \end{aligned}$$

Therefore, we have

$$\rho_E((m, M), (m^*, M^*)) = \frac{|c_0^* - c_0|}{\|\text{grad}U(m + \lambda_0(m^* - m), M + \lambda_0(M^* - M))\|},$$

whence we obtain

$$\begin{aligned} &\frac{|c_0^* - c_0|}{\sup\{\|\text{grad}U(m', M')\|, (m', M') \in D\}} \\ &= \text{const}_1 \leq \rho_E((m, M), (m^*, M^*)) \\ &\leq \text{const}_2 = \frac{|c_0^* - c_0|}{\inf\{\|\text{grad}U(m', M')\|, (m', M') \in D\}}. \end{aligned}$$

From the last inequalities, we get:

$$\begin{aligned} (5) \quad \text{const}_1 &\leq \inf\left\{\inf\left\{\rho_E((m^*, M^*), (m, M)), (m^*, M^*) \in \gamma_{c_0^*}\right\}, (m, M) \in \gamma_{c_0}\right\} \\ &= \rho_E(\gamma_{c_0^*}, \gamma_{c_0}) \end{aligned}$$

and

$$(6) \quad \sup\left\{\inf\left\{\rho_E((m^*, M^*), (m, M)), (m^*, M^*) \in \gamma_{c_0^*}\right\}, (m, M) \in \gamma_{c_0}\right\} \leq \text{const}_2.$$

By analogy with (6) we conclude that

$$(7) \quad \sup\left\{\inf\left\{\rho_E((m^*, M^*), (m, M)), (m, M) \in \gamma_{c_0}\right\}, (m^*, M^*) \in \gamma_{c_0^*}\right\} \leq \text{const}_2.$$

Using (6) and (7) we have

$$(8) \quad \rho_H(\gamma_{c_0^*}, \gamma_{c_0}) = \max \left\{ \sup \left\{ \inf \left\{ \rho_E \left((m^*, M^*), (m, M) \right), (m^*, M^*) \in \gamma_{c_0^*} \right\}, (m, M) \in \gamma_{c_0} \right\}, \right. \\ \left. \sup \left\{ \inf \left\{ \rho_E \left((m^*, M^*), (m, M) \right), (m, M) \in \gamma_{c_0} \right\}, (m^*, M^*) \in \gamma_{c_0^*} \right\} \right\} \leq const_2.$$

Therefore, from (5) and (8) it follows

$$const_1 \leq \rho_E(\gamma_{c_0^*}, \gamma_{c_0}) \leq \rho_H(\gamma_{c_0^*}, \gamma_{c_0}) \leq const_2$$

and hence

$$\frac{\rho_H(\gamma_{c_0^*}, \gamma_{c_0})}{\rho_E(\gamma_{c_0^*}, \gamma_{c_0})} \leq \frac{const_2}{const_1} = \frac{\sup \left\{ \left\| \text{grad}U(m', M') \right\|, (m', M') \in D \right\}}{\inf \left\{ \left\| \text{grad}U(m', M') \right\|, (m', M') \in D \right\}} = \kappa.$$

The theorem is proved.

As corollary of the last theorem we obtain the following theorem.

Theorem 4. *The solution of problem (1), (2), (3) is orbital Hausdorff stable.*

Proof. Let ε be arbitrary positive constant, $c_0 = U(m_0, M_0)$ and the constants c_1 and c_2 satisfy the inequalities $0 < c_1 < c_0 < c_2$. For example let $c_1 = \frac{1}{2}c_0$ and $c_2 = \frac{3}{2}c_0$. Then, according to Theorem 3, it follows that the system (1), (2) is orbital gravitating in the domain $D = D_{c_2} \setminus D_{c_1}$ with a constant $\kappa = \kappa(D) = \kappa(c_1, c_2) = \kappa(c_0) = \kappa(m_0, M_0)$. Then for every point $(m_0^*, M_0^*) \in D$ such that

$$\rho_E \left((m_0^*, M_0^*), (m_0, M_0) \right) < \frac{\varepsilon}{\kappa}$$

we have

$$\rho_H(\gamma_{c_0^*}, \gamma_{c_0}) \leq \kappa \rho_E(\gamma_{c_0^*}, \gamma_{c_0}) \leq \kappa \rho_E \left((m_0^*, M_0^*), (m_0, M_0) \right) < \varepsilon,$$

where $c_0^* = U(m_0^*, M_0^*)$.

The theorem is proved.

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