

## Structural Identification of Quasi White Noise Linear Models

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### Abstract

*This paper shows that within the parametric admissible region of the Box and Jenkins ARMA( $p,q$ ) structures there is a sub-region where the classical identification procedure via ACF and PACF does not work properly. We define this sub-space the “Quasi White Noise region” and show how the bootstrap procedure can be used to improve the performance of the structural identification for series located in this particular region. A simulation study was carried out and a comparison between the traditional and the bootstrap procedures is presented.*

**Keywords:** Box and Jenkins, Bootstrap, Quasi White Noise Process

### 1. Introduction

The Box and Jenkins approach, proposed in 1970, [1], as a general procedure to develop time series models for forecasting and control, consists of three stages, namely: structural identification, model parameter estimation and goodness of fitting tests. The structural identification is carried out via joint use of the autocorrelation function (ACF for short) and the partial autocorrelation function (PACF for short). However, in this particular stage of the procedure, there is a chances of the one assumes that the time series in study has been generated by a white noise type of stochastic process, when in fact, this assumption is not true. In other words the straight forward application of the identification procedure leads one to admit the series as being a white noise, yet, the model parameters are located in a particular region of the parametric space with properties not defected by the classical procedure. We define a time series with this property as “Quasi White Noise” series (QWN) from now on.

The bootstrap is a non-parametric computational intensive statistical procedure (CIS for short), proposed in 1979, [2] and [3], which allows the evaluation of the variability of any statistics based on information of a single sample. It is recommended for situations where the standard procedures are not available or are difficult to be obtained in analytical terms. This technique can be used in problems characterized by both; finite sample or big sample size, as they produce better results in the former and as good result as the usual asymptotic in the latter (\*). In this paper we formally propose the use of bootstrap as an additional technique to be used in the model identification stage of Box and Jenkins ARIMA structures. The remainder of the paper is organized as follows. In section 2 we address the problems associated with the identification of time series showing the QWN property, while in section 3 we propose the use of bootstrap for QWN series. In section 4 we describe a simulation study carried out and the main conclusions of the proposed procedure are drawn. The paper is concluded with an appendix containing the results and plots from the simulation study.

### 2. Classical Identification of Arima Structures and the Qwn Series

It is well known that the identification of the ARIMA structure of the process generating a given series is carried out via the joint use of the  $(1-\alpha)\%$  confidence intervals for the ACF ( $\rho_k$ ) and the PACF ( $\Phi_{kk}$ ) given by (see Box and Jenkins [1] for details:

$$I = [-z_{(1-\alpha/2)} \cdot \sqrt{\widehat{V}(\widehat{\rho}_k)} ; z_{(1-\alpha/2)} \cdot \sqrt{\widehat{V}(\widehat{\rho}_k)} ] \text{ for } \rho_k, \text{ and}$$

$$II = [-z_{(1-\alpha/2)} \cdot \frac{1}{\sqrt{n}} ; z_{(1-\alpha/2)} \cdot \frac{1}{\sqrt{n}} ] \text{ for } \phi_{kk}$$

As described in Box and Jenkins the intervals above are used to test, respectively, the following hypothesis:  $H_{01}: \rho_k = 0$  and  $H_{02}: \Phi_{kk} = 0$ . Therefore, the joint use of both: the sample correlogram (graph  $\rho_k \times k$ ) and the sample partial correlogram (graph  $\Phi_{kk} \times k$ ) and the application of the tests for every  $k = 1, 2, \dots$  results in the identification of an ARIMA structure candidate to model the series under study. However, situations may occur whereby the sample ACF and PACF are different of zero; however their values are not big enough to reject the null hypothesis of either one or both tests. In this particular case, the straightforward use of the classical procedure would mislead us in accepting the series as being generated by a white noise process. In reality, we are facing models whose parameters are located in particular regions of the parametric space whose theoretical absolute values of  $\rho_k$  and  $\phi_{kk}$  are small. Models presenting this property are the object of this paper and are formally defined below. Let  $T = \{1, 2, 3, \dots, n\}$  represent a finite set of natural numbers and I and II above the  $(1-\alpha)\%$  confidence interval to test, respectively:  $\rho_k = 0$  and  $\phi_{kk} = 0$ . We define the QWN process as:

**Def.:** The QWN is as an ergotic stochastic process whose absolute values of  $\rho_k$  and  $\phi_{kk}$ , though different of zero, are located within intervals I and II respectively.

The regions of the stationary parametric space of the following structures ARMA(p,q) , i.e.: AR(1), AR(2), MA(1), MA(2) and ARMA(1,1) where the QWN processes exist are marked below, in figures I to V through the sets Q and  $Q^2$  within each one of the admissible (stationary and invertible) regions. The corresponding proofs of the existence of such regions can be found in reference [4]. Then denoting  $c = f(\alpha, n)$  where  $f(\cdot)$  is a non-negative function of the confidence level  $\alpha$  and of the series size n, we have, for each structure:

**AR(1)**

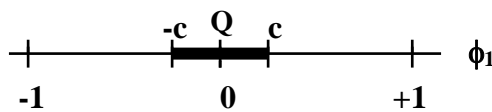


Figure I - AR(1) :  $Q = \{ \phi_1 \in \mathfrak{R} ; |\phi_1| < c \}$

**AR(2)**

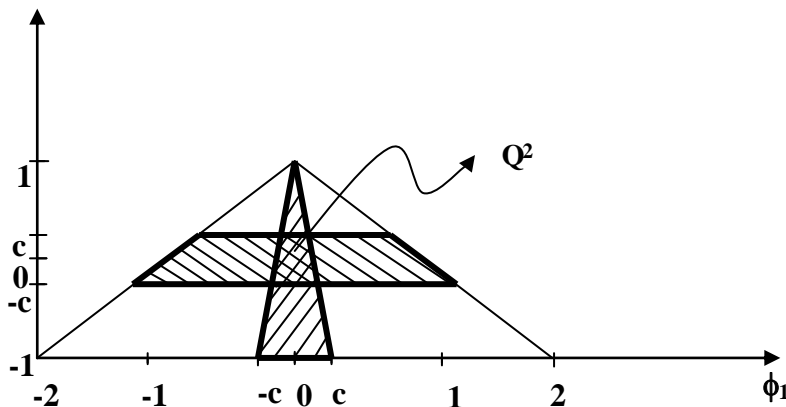


Figure II - AR(2) :  $Q^2 = \{ (\phi_1, \phi_2) \in \mathfrak{R}^2 ; |\phi_1| < c(1 - \phi_2) \text{ and } |\phi_2| < c \}$

MA(1)

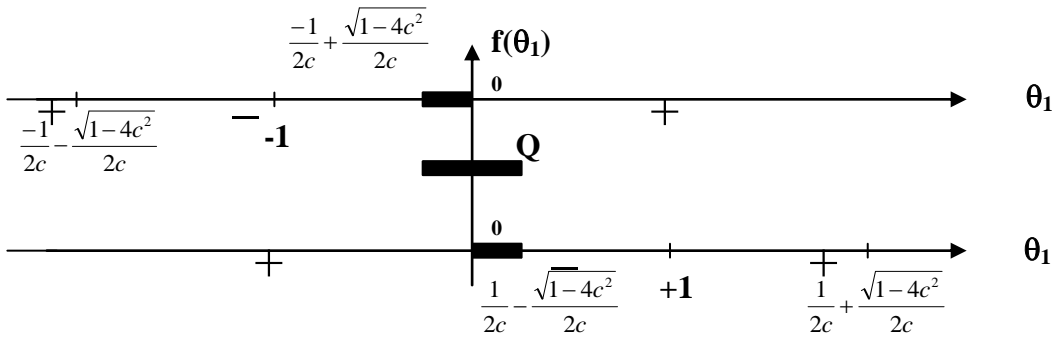


Figure III - MA(1) :  $Q = \{ \theta_1 \in \mathfrak{R} ; |\theta_1| < \frac{1}{2c} - \frac{\sqrt{1-4c^2}}{2c} \}$

MA(2)

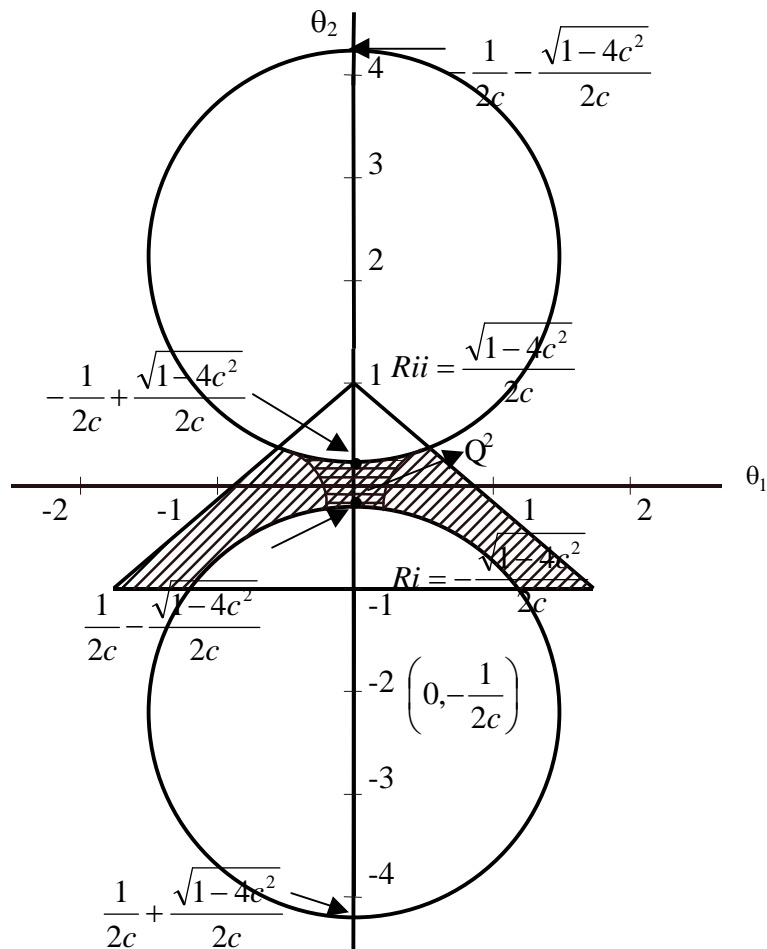


Figure IV - MA(2):  $Q^2 = \{ (\theta_1, \theta_2) \in \mathfrak{R}^2 ; c\theta_1^2 + c\theta_2^2 + \theta_1 - \theta_1\theta_2 + c > 0, c\theta_1^2 + c\theta_2^2 - \theta_1 + \theta_1\theta_2 + c > 0, \theta_1^2 + \theta_2^2 + \frac{1}{c}\theta_2 + 1 > 0 \text{ and } \theta_1^2 + \theta_2^2 - \frac{1}{c}\theta_2 + 1 > 0 \}$

ARMA(1,1)

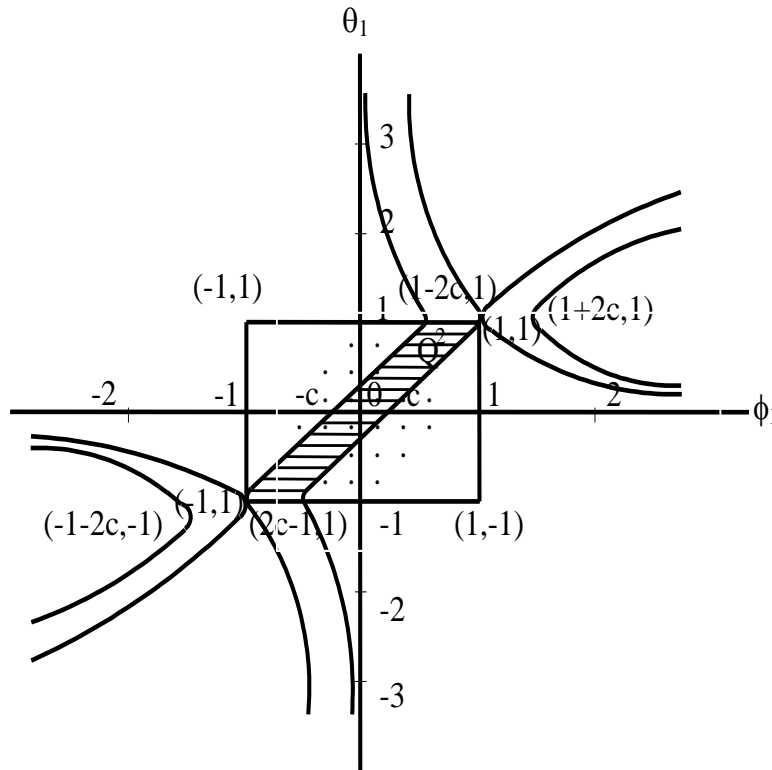
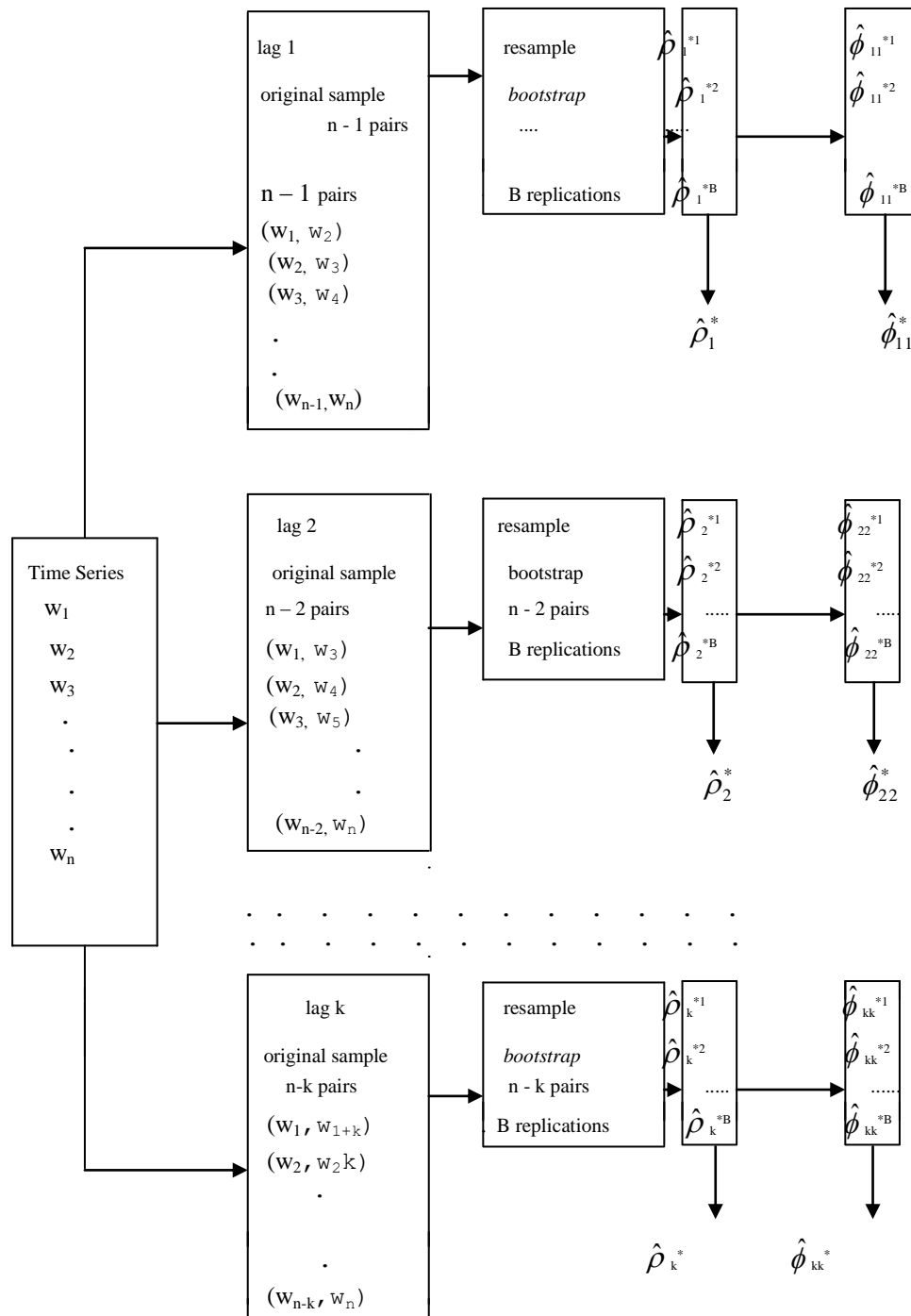


Figure V - ARMA(1,1) :  $Q^2 = \{(\phi_1, \theta_1) \in \mathfrak{R}^2 ; (\phi_1 - c)\theta_1^2 - (\phi_1^2 - 2c\phi_1 + 1)\phi_1 + \phi_1 - c < 0, (\phi_1 + c)\theta_1^2 - (\phi_1^2 + 2c\phi_1 + 1)\theta_1 + \phi_1 + c > 0\}$

3. Using the Bootstrap in Structural Identification

As mentioned before the bootstrap can be very useful in helping the identification of ARMA(p,q) structures, [6] and [5]. Models with parameters within of the QWN region, in particular, can be better identified by the use of the bootstrap. In order to use this technique in the structural identification of process generating the series under study one must first calculate the bootstrap’s distributions of  $\hat{\rho}_k$  and  $\hat{\Phi}_{kk}$ . The algorithm used to generate such distributions is as shown in the flowchart of figure VI. Once these distributions are obtained, one can use them to estimate probability intervals for the true unknown parameters. The bootstrap interval for the parameters ( $\rho_k$  and  $\Phi_{kk}$ ) used in this study is the “Bias Corrected Percentile Interval” as described in [3] and has the following expression,  $[CDF^{-1}(\Phi(2z_0 - z_\alpha)); CDF^{-1}(\Phi(2z_0 + z_\alpha))]$ , which is used for either one  $\rho_k$  and  $\Phi_{kk}$ , depending on the bootstrap distribution considered.



**Figure VI - Flowchart of Algorithm Used to Generate the Bootstrap Distributions of  $\hat{\rho}_k$  AND  $\hat{\phi}_{kk}$**

**4. Study of Simulation and Conclusions**

We artificially generated time series corresponding to models within the five ARMA(p,q) structures considered in this study namely: AR(1), AR(2), MA(1), MA(2) and ARMA(1,1). The positions of the parameters  $\Phi$ 's and  $\theta$ 's within of the respective parametric spaces of each one of the five structures are shown in figures VII to XI. The number of models for each structure was: 14 AR(1); 12 AR(2); 14 MA(1); 19 MA(2) and 24 ARMA(1,1). The residual variance was fixed at  $\sigma_a^2 = 0.1$  for all series and a Gaussian distribution with mean zero for the noise was assumed throughout [4]. In each experiment were worked 100 Monte Carlo replications and 1000 bootstrap replications.

In the evaluation of the procedure classical versus the bootstrap procedure was calculated the empirical power of the hypothesis tests concerning the ACF and PACF. In the classical procedure the following null hypothesis were considered:

$$H_{01}: \rho_k = 0 \text{ and } H_{02}: \phi_{kk} = 0$$

and was checked whether intervals I and II include the zero value. Concerning the bootstrap procedure the null hypothesis were the following:

$$H_{01}: [\hat{\rho}_k^{*lo}, \hat{\rho}_k^{*up}] \supset 0 \text{ and } H_{02}: [\hat{\phi}_{kk}^{*lo}, \hat{\phi}_{kk}^{*up}] \supset 0$$

Where the superscripts *\*lo* and *\*up* denote the bounds upper and lower for the corresponding parameters, and, the above intervals are the BC percentile intervals defined previously.

Was, also, used the Euclidean metric to evaluate the distance between the number of coverage of the true parameter by the classical intervals and the number of expected coverage for each simulated model [7]. As were considered the first 3 lags ( $k = 1, 2, 3$ ), then they compose jointly the number of coverage as a single point. Likewise the expected coverage jointly was also considered a single point and the “distance” between these two points was evaluated by the Euclidean metric. In a similar way, was also evaluated the “distance” between the single point corresponding to the joint coverage for the three first lags with the bootstrap intervals and a second single point corresponding to the joint expected coverage for the first three lags. Incidentally, this second single point, formed via expected coverage is the same for both: classical and bootstrap procedures. The graphs these distances and the locations of the parameters of models in the parameter space for each one of the ARMA(p, q) structures simulated are shown in the figures VII to XXI of appendix I. The estimated standard errors of  $\rho_k$  and  $\phi_{kk}$  for the first three lags are as shown in appendix II. From the results of the simulation study we can draw the following conclusions:

- (I) The BC percentile interval has a greater power of rejecting the null hypothesis of zero values for the ACF and PACF (when they are false), especially when the models have their parameters within the QWN region. For models with parameters near to the boundaries of the stationary and invertibility regions, this power decreases, particularly for the PACF. This can be easily seen in the corresponding plots of the Euclidean distances in appendix I, where the distances of the bootstrap points to the corresponding expected ones are, in general, smaller than the classical distances.
- (II) The bootstrap estimates of  $\hat{\rho}_k$  and  $\hat{\phi}_{kk}$  are better for models located in the QWN regions (or near them), as can be seen by the estimates of these quantities shown in tables 1 to 5 of appendix II.
- (III) For time series generated by real white noise process, the performance of the bootstrap method is superior to the classical procedure and is according to the estimation of the standard error, as shown in table 6 of the appendix II.

## References

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Appendix I

Location of model's parameters in the parameter space and Euclidean distance between the bootstrap (B) and the expected value and between the classical (C) and the expected value for structure's models.

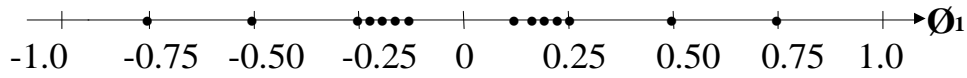


Figure VII - Location of Model's Parameters in the Parameter Space for the AR (1) Structure

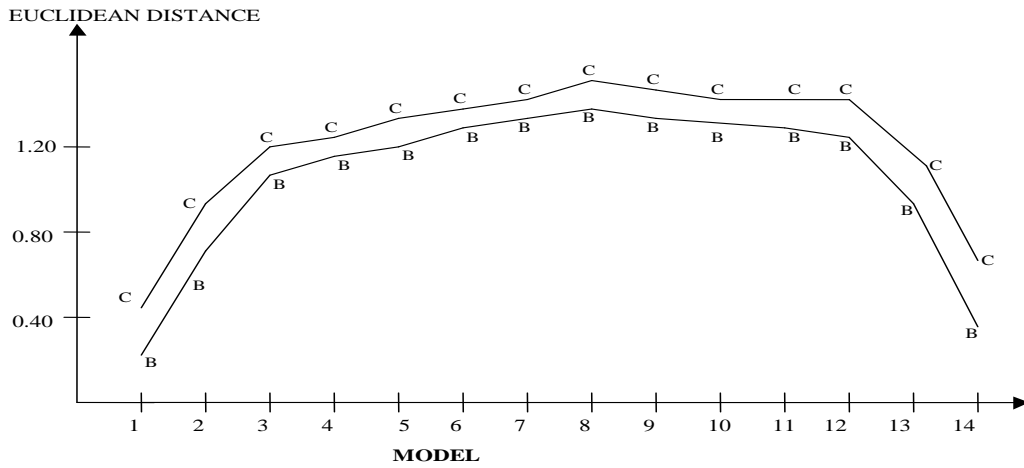


Figure VIII - Euclidean Distance between the Bootstrap (B) and the Expected value and between the Classical (C) and the Expected Value for Models of the AR (1) Structure for ACF

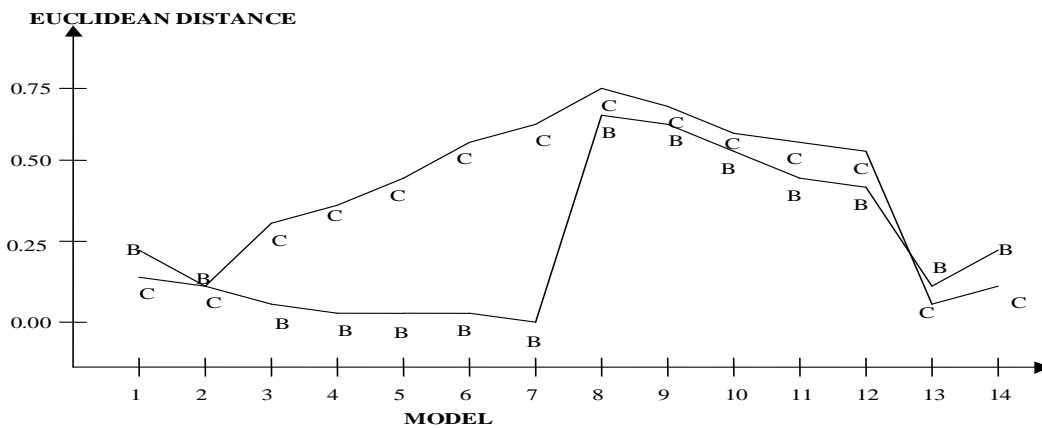


Figure IX - Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected Value for Models of the AR (1) Structure for PACF

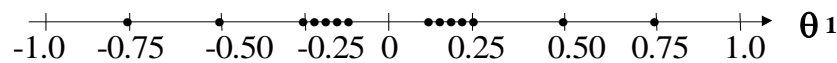


Figure X - Location of Model's Parameters in the Parameter Space for the MA (1) structure

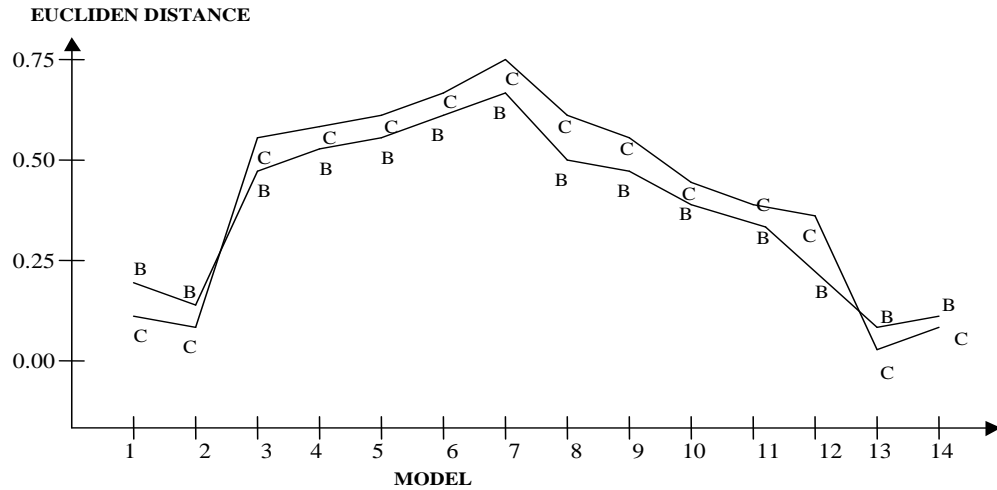


Figure XI – Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected Value for Models of the MA(1) Structure for ACF

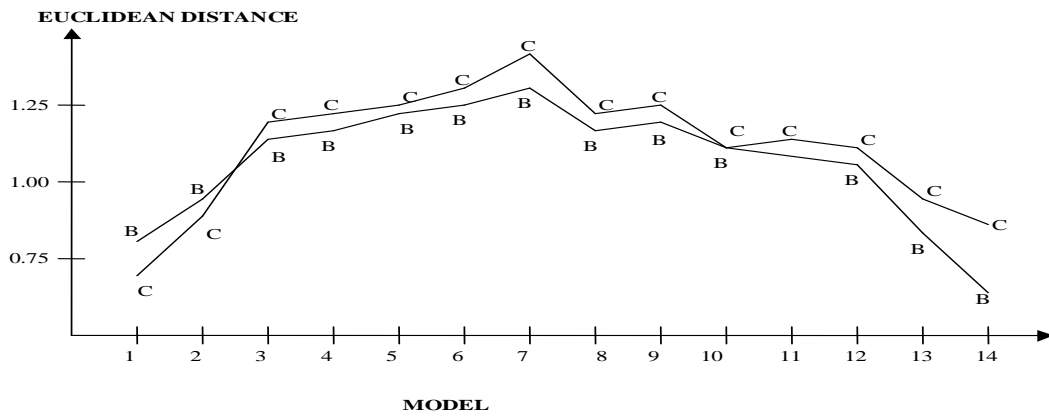


Figure XII - Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected Value for Models of the MA (1) Structure for PACF

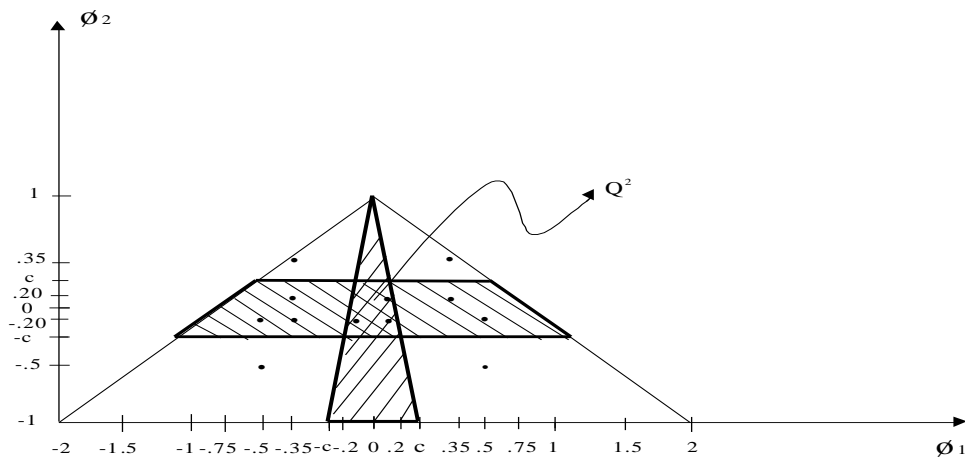


Figure XIII - Location of Model's Parameters in the Parameter Space for the AR (2) Structure



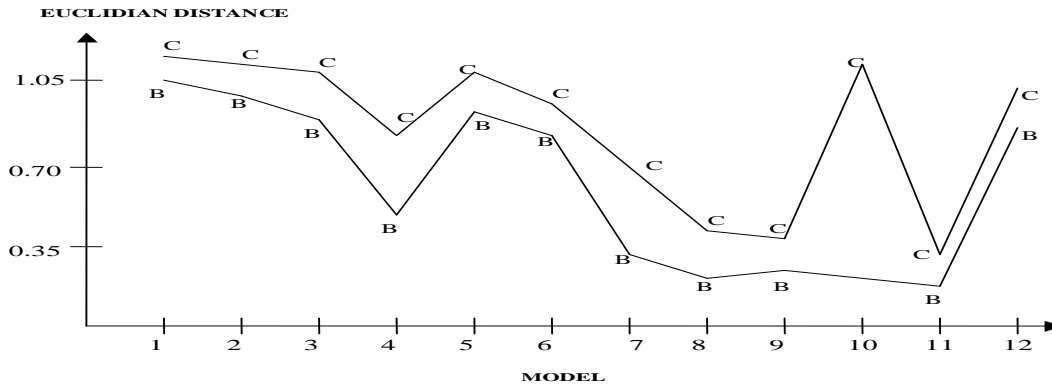


Figure XIV- Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected Value for Models of the AR (2) Structure for ACF

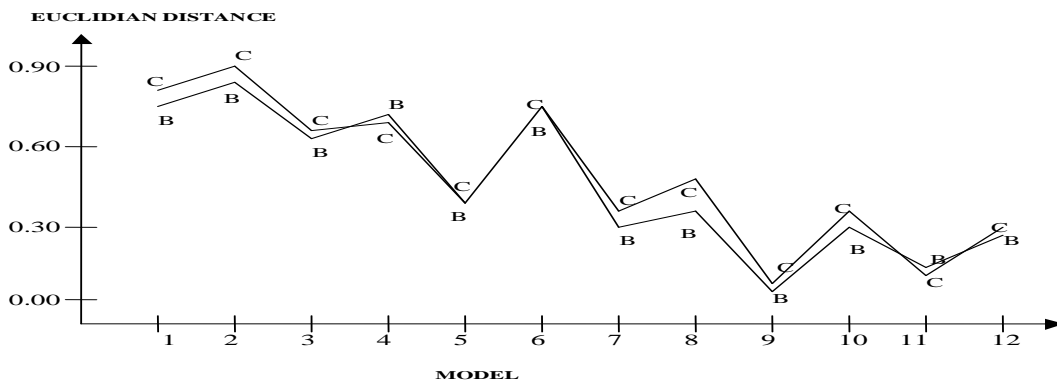


Figure XV - Euclidean Distance between the Bootstrap (B) and the Expected Value and Between the Classical (C) and the Expected Value for Models of the AR (2) Structure for PACF

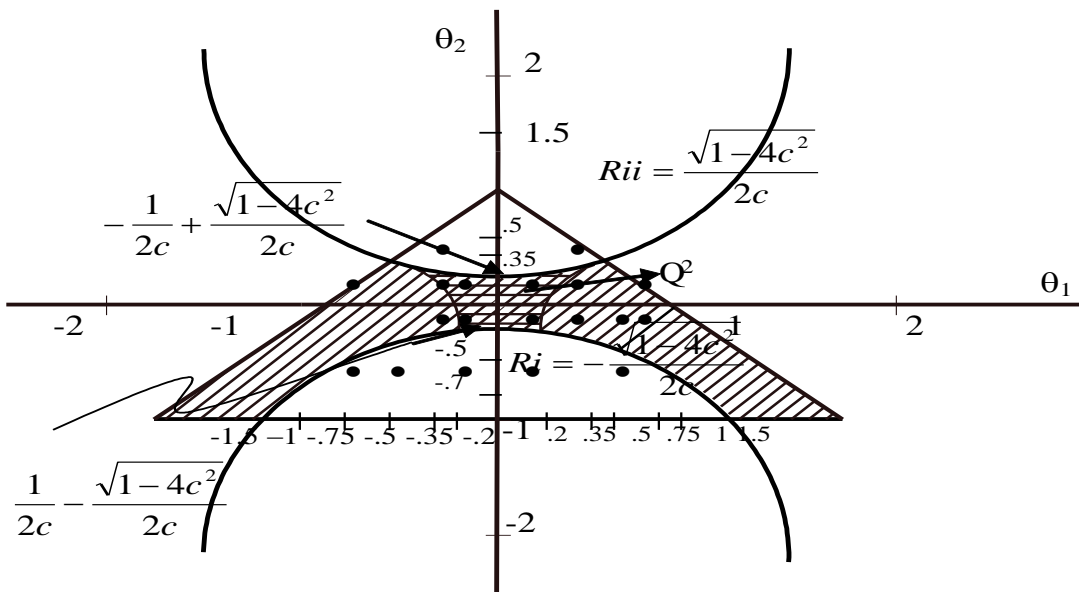
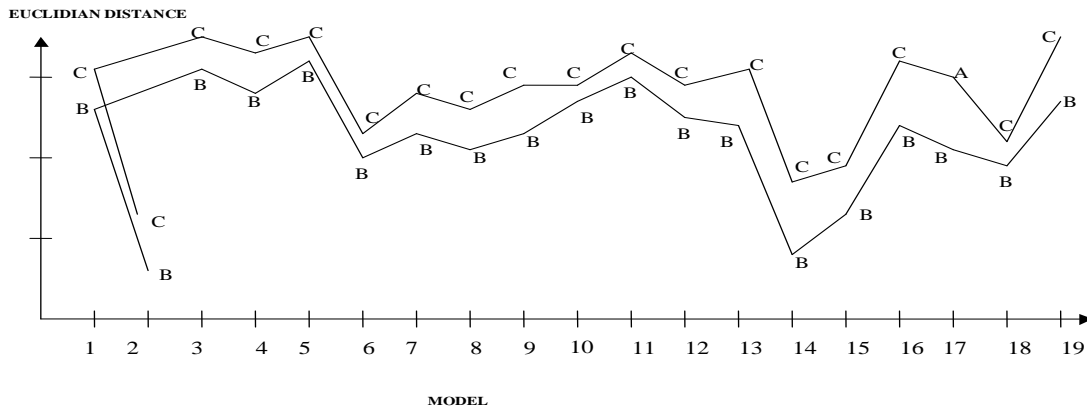
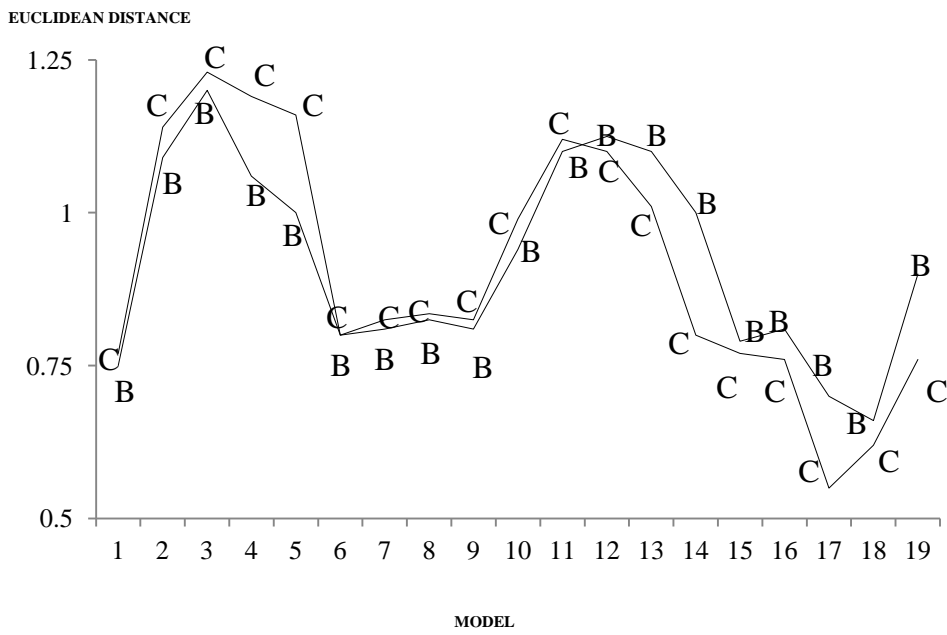


Figure XVI - Location of Model's Parameters in the Parameter Space for the MA (2) Structure



**Figure XVII: Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected Value for Models of the MA(2) Structure for ACF**



**Figure XVIII - Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected value for Models of the MA (2) Structure for PACF**

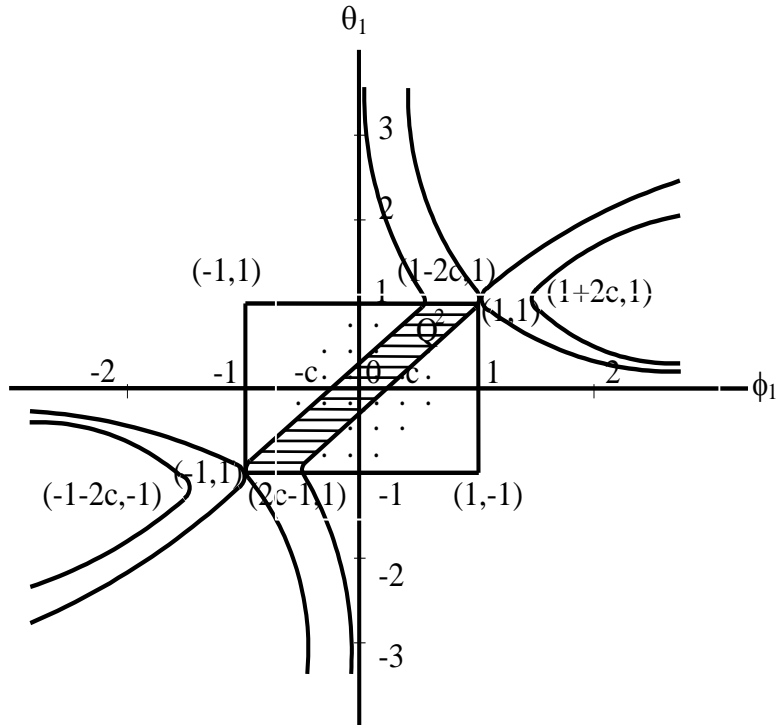


Figure XIX - Location of Model's Parameters in the Parameter Space for the ARMA (1,1) Structure

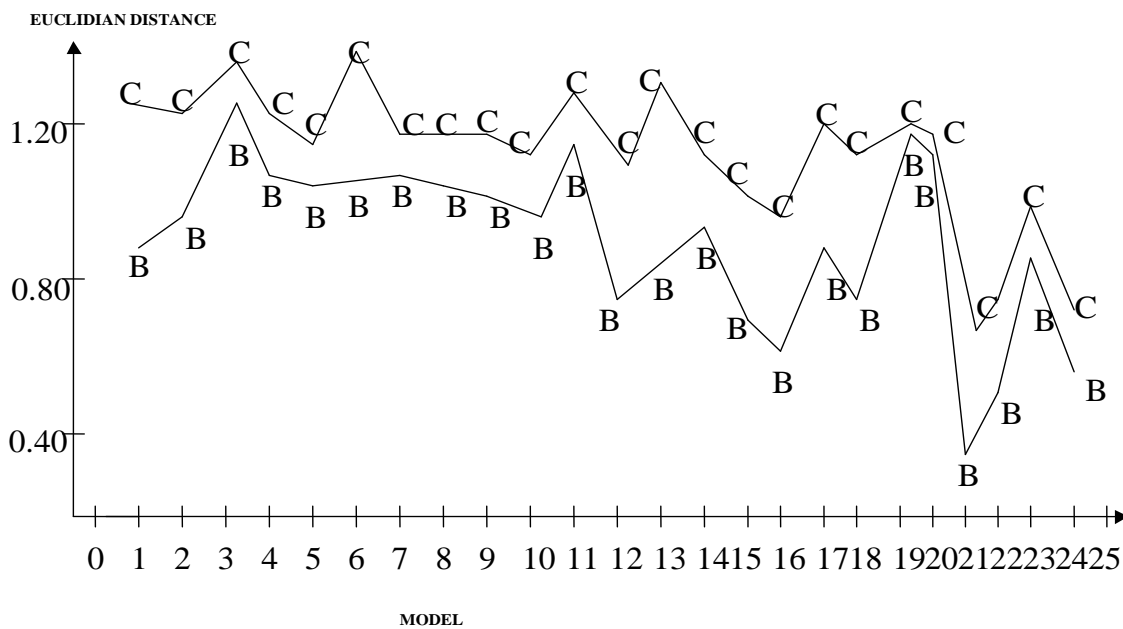
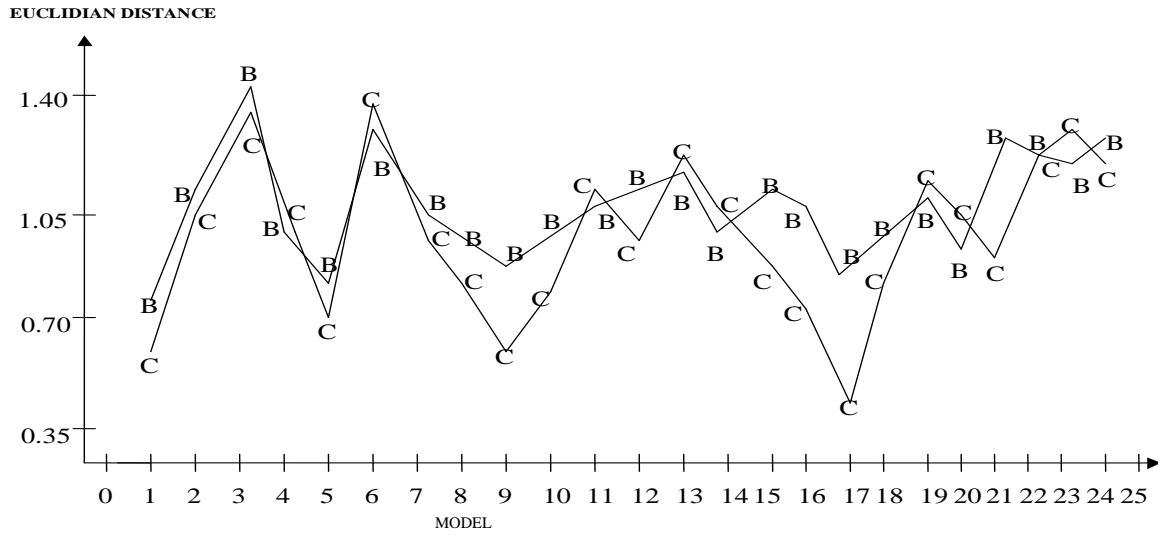


Figure XX - Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected value for Models of the ARMA (1, 1) Structure for ACF



**Figure XXI – Euclidean Distance between the Bootstrap (B) and the Expected Value and between the Classical (C) and the Expected value for Models of the ARMA(1,1) Structure for PACF**

**Appendix II: Standard errors estimates of the classical and bootstrap procedures for  $\hat{\rho}_k$  and  $\hat{\Phi}_{kk}$ , lags  $k = 1, 2, 3$**

**Tab. 1 – Models of the AR (1) Structure**

Model – n Parameters	$\sigma(\hat{\rho}_k)$	$s(\hat{\rho}_k)$	$s(\hat{\rho}^*_k)$	$\sigma(\hat{\Phi}_{kk})$	$s(\hat{\Phi}_{kk})$	$s(\hat{\Phi}^*_{kk})$
AR(1) n=50 $\Phi_1=0.125$	.136	.141	.135	.136	.141	.135
	.140	.145	.133	.134	.141	.137
	.135	.148	.131	.139	.141	.138
AR(1) n=50 $\Phi_1=0.150$	.136	.141	.135	.136	.141	.135
	.141	.145	.133	.134	.141	.137
	.135	.148	.131	.139	.141	.138
AR(1) n=50 $\Phi_1=0.200$	.135	.141	.136	.135	.141	.136
	.142	.147	.133	.134	.141	.139
	.135	.150	.130	.139	.141	.139
AR(1) n=50 $\Phi_1=0.225$	.135	.141	.137	.135	.141	.137
	.143	.148	.133	.133	.141	.140
	.136	.151	.130	.139	.141	.140
AR(1) n=50 $\Phi_1=0.250$	.134	.141	.137	.134	.141	.137
	.144	.149	.133	.133	.141	.141
	.137	.152	.130	.139	.141	.141
AR(1) n=50 $\Phi_1=0.500$	.123	.141	.146	.123	.141	.146
	.153	.166	.132	.134	.141	.167
	.151	.171	.126	.137	.141	.163
AR(1) n=50 $\Phi_1=0.750$	.102	.141	.153	.102	.141	.153
	.151	.193	.136	.135	.141	.255
	.172	.211	.125	.136	.141	.239
AR(1) n=50 $\Phi_1=-.125$	.133	.141	.135	.133	.141	.135
	.142	.147	.134	.139	.141	.140
	.139	.149	.132	.138	.141	.141
AR(1) n=50 $\Phi_1=-.150$	.133	.141	.135	.133	.141	.135
	.143	.148	.134	.140	.141	.141
	.140	.150	.132	.138	.141	.142
AR(1) n=50 $\Phi_1=-.200$	.131	.141	.136	.131	.141	.136
	.145	.150	.134	.141	.141	.143
	.142	.152	.132	.137	.141	.145
AR(1) n=50 $\Phi_1=-.225$	.130	.141	.136	.130	.141	.136
	.146	.151	.134	.142	.141	.145
	.143	.154	.132	.136	.141	.146
AR(1) n=50 $\Phi_1=-.250$	.129	.141	.137	.129	.141	.137
	.147	.152	.134	.142	.141	.147
	.144	.155	.132	.136	.141	.148
AR(1) n=50 $\Phi_1=-.500$	.115	.141	.146	.115	.141	.146
	.159	.172	.134	.147	.141	.182
	.162	.179	.131	.131	.141	.181
AR(1) n=50 $\Phi_1=-.750$	.098	.141	.156	.098	.141	.156
	.161	.201	.139	.146	.141	.299
	.181	.224	.131	.124	.141	.288

**Tab. 2 – Models of the MA (1) Structure**

<b>Model – n Parameters</b>	$\sigma(\hat{\rho}_k)$	$s(\hat{\rho}_k)$	$s(\hat{\rho}^*_{k})$	$\sigma(\hat{\Phi}_{kk})$	$s(\hat{\Phi}_{kk})$	$s(\hat{\Phi}^*_{kk})$
MA(1)n=50 $\theta_1=0.125$	.132	.141	.135	.132	.141	.135
	.142	.146	.134	.139	.141	.140
	.139	.149	.132	.138	.141	.141
MA(1)n=50 $\theta_1=0.150$	.130	.141	.135	.130	.141	.135
	.142	.147	.134	.139	.141	.141
	.140	.150	.132	.137	.141	.142
MA(1)n=50 $\theta_1=0.200$	.127	.141	.136	.127	.141	.136
	.144	.149	.134	.140	.141	.143
	.142	.152	.132	.136	.141	.145
MA(1)n=50 $\theta_1=0.225$	.125	.141	.136	.125	.141	.136
	.145	.150	.134	.140	.141	.144
	.143	.153	.132	.135	.141	.146
MA(1)n=50 $\theta_1=0.250$	.124	.141	.137	.124	.141	.137
	.146	.151	.134	.140	.141	.146
	.144	.154	.132	.135	.141	.148
MA(1)n=50 $\theta_1=0.500$	.106	.141	.142	.106	.141	.142
	.155	.162	.134	.134	.141	.162
	.155	.165	.132	.126	.141	.171
MA(1)n=50 $\theta_1=0.750$	.097	.141	.146	.097	.141	.146
	.162	.170	.134	.124	.141	.174
	.161	.173	.132	.113	.141	.194
MA(1)n=50 $\theta_1=-.125$	.135	.141	.135	.135	.141	.135
	.140	.145	.133	.134	.141	.137
	.135	.148	.131	.139	.141	.138
MA(1)n=50 $\theta_1=-.150$	.134	.141	.135	.134	.141	.135
	.140	.145	.133	.134	.141	.137
	.135	.148	.131	.139	.141	.138
MA(1)n=50 $\theta_1=-.200$	.132	.141	.136	.132	.141	.136
	.142	.147	.133	.133	.141	.139
	.136	.150	.130	.138	.141	.140
MA(1)n=50 $\theta_1=-.225$	.130	.141	.137	.130	.141	.137
	.142	.147	.133	.132	.141	.140
	.136	.151	.130	.137	.141	.141
MA(1)n=50 $\theta_1=-.250$	.129	.141	.137	.129	.141	.137
	.143	.148	.133	.132	.141	.141
	.137	.151	.130	.137	.141	.142
MA(1)n=50 $\theta_1=-.500$	.114	.141	.144	.114	.141	.144
	.152	.159	.132	.124	.141	.153
	.144	.162	.128	.126	.141	.161
MA(1)n=50 $\theta_1=-.750$	.106	.141	.149	.106	.141	.159
	.158	.166	.131	.116	.141	.164
	.149	.170	.127	.111	.141	.183

**Tab. 3 – Models of the AR (2) Structure**

<b>Model – n Parameters</b>	$\sigma(\hat{\rho}_k)$	$s(\hat{\rho}_k)$	$s(\hat{\rho}^*_{kk})$	$\sigma(\hat{\Phi}_{kk})$	$s(\hat{\Phi}_{kk})$	$s(\hat{\Phi}^*_{kk})$
AR(2)n=50	.115	.141	.136	.115	.141	.136
$\Phi_1= 0.200$	.136	.146	.136	.128	.141	.140
$\Phi_2= -0.200$	.138	.153	.131	.131	.141	.147
AR(2)n=50	.158	.141	.136	.158	.141	.136
$\Phi_1= 0.200$	.142	.149	.134	.134	.141	.143
$\Phi_2= 0.200$	.141	.155	.129	.146	.141	.142
AR(2)n=50	.111	.141	.135	.111	.141	.135
$\Phi_1= -0.200$	.138	.147	.137	.134	.141	.143
$\Phi_2= -0.200$	.145	.154	.133	.133	.141	.151
AR(2)n=50	.142	.141	.142	.142	.141	.142
$\Phi_1= -0.350$	.156	.167	.135	.146	.141	.173
$\Phi_2= 0.200$	.159	.179	.131	.135	.141	.173
AR(2)n=50	.107	.141	.139	.107	.141	.139
$\Phi_1= -0.350$	.144	.154	.135	.139	.141	.150
$\Phi_2= -0.200$	.150	.159	.134	.132	.141	.161
AR(2)n=50	.151	.141	.141	.151	.141	.141
$\Phi_1= 0.350$	.147	.159	.135	.132	.141	.159
$\Phi_2= 0.200$	.151	.169	.127	.146	.141	.155
AR(2)n=50	.169	.141	.139	.169	.141	.139
$\Phi_1= 0.350$	.144	.166	.138	.128	.141	.175
$\Phi_2= 0.350$	.167	.185	.127	.149	.141	.177
AR(2)n=50	.155	.141	.144	.155	.141	.144
$\Phi_1= -0.350$	.156	.176	.139	.144	.141	.202
$\Phi_2= 0.350$	.170	.200	.132	.133	.141	.209
AR(2)n=50	.076	.141	.141	.076	.141	.141
$\Phi_1= -0.500$	.129	.157	.140	.125	.141	.155
$\Phi_2= -0.500$	.153	.171	.138	.128	.141	.216
AR(2)n=50	.101	.141	.143	.101	.141	.143
$\Phi_1= -0.500$	.152	.164	.134	.142	.141	.165
$\Phi_2= -0.200$	.157	.167	.133	.129	.141	.177
AR(2)n=50	.081	.141	.142	.081	.141	.142
$\Phi_1= 0.500$	.127	.155	.139	.119	.141	.152
$\Phi_2= -0.500$	.136	.171	.137	.117	.141	.210
AR(2)n=50	.107	.141	.144	.107	.141	.144
$\Phi_1= 0.500$	.147	.160	.131	.131	.141	.155
$\Phi_2= -0.200$	.144	.163	.130	.128	.141	.166

**Tab. 4 – Models of the MA (2) Structure**

<b>Model – n Parameters</b>	$\sigma(\hat{\rho}_k)$	$s(\hat{\rho}_k)$	$s(\hat{\rho}^*_{k})$	$\sigma(\hat{\Phi}_{kk})$	$s(\hat{\Phi}_{kk})$	$s(\hat{\Phi}^*_{kk})$
MA(2)n=50	.145	.141	.136	.145	.141	.136
$\theta_1= 0.200$	.141	.152	.134	.145	.141	.146
$\theta_2= -0.200$	.144	.157	.131	.139	.141	.147
MA(2)n=50	.172	.141	.137	.172	.141	.137
$\theta_1= 0.200$	.122	.154	.138	.138	.141	.154
$\theta_2= -0.500$	.152	.169	.130	.151	.141	.158
MA(2)n=50	.150	.141	.136	.150	.141	.136
$\theta_1= -0.200$	.138	.148	.133	.135	.141	.140
$\theta_2= -0.200$	.137	.152	.129	.143	.141	.140
MA(2)n=50	.113	.141	.135	.113	.141	.135
$\theta_1= 0.200$	.134	.146	.137	.127	.141	.143
$\theta_2= 0.200$	.145	.154	.132	.129	.141	.149
MA(2)n=50	.117	.141	.135	.117	.141	.135
$\theta_1= -0.200$	.132	.145	.137	.122	.141	.140
$\theta_2= 0.200$	.141	.153	.131	.131	.141	.146
MA(2)n=50	.177	.141	.135	.177	.141	.135
$\theta_1= -0.200$	.117	.149	.137	.126	.141	.146
$\theta_2= -0.500$	.146	.163	.128	.154	.141	.150
MA(2)n=50	.109	.141	.137	.109	.141	.137
$\theta_1= 0.350$	.140	.151	.137	.126	.141	.147
$\theta_2= 0.200$	.149	.157	.132	.124	.141	.157
MA(2)n=50	.105	.141	.136	.105	.141	.136
$\theta_1= 0.350$	.128	.147	.140	.117	.141	.146
$\theta_2= 0.350$	.152	.159	.132	.119	.141	.159
MA(2)n=50	.109	.141	.137	.109	.141	.137
$\theta_1= -0.350$	.140	.151	.137	.126	.141	.147
$\theta_2= 0.200$	.149	.157	.132	.124	.141	.157
MA(2)n=50	.112	.141	.137	.112	.141	.137
$\theta_1= -0.350$	.126	.146	.139	.109	.141	.144
$\theta_2= 0.350$	.147	.160	.130	.122	.141	.157
MA(2)n=50	.133	.141	.141	.133	.141	.141
$\theta_1= -0.350$	.144	.155	.132	.140	.141	.149
$\theta_2= -0.200$	.142	.159	.128	.138	.141	.148
MA(2)n=50	.126	.141	.140	.126	.141	.140
$\theta_1= 0.350$	.148	.161	.134	.152	.141	.159
$\theta_2= -0.200$	.152	.165	.132	.135	.141	.160
MA(2)n=50	.108	.141	.145	.108	.141	.145
$\theta_1= 0.500$	.155	.169	.134	.151	.141	.174
$\theta_2= -0.200$	.160	.173	.132	.132	.141	.178
MA(2)n=50	.120	.141	.146	.120	.141	.146
$\theta_1= 0.500$	.143	.174	.137	.178	.141	.190
$\theta_2= -0.500$	.170	.185	.130	.127	.141	.186



**Tab. 4 (cont.) – MA (2)**

MA(2)n=50	.127	.141	.146	.127	.141	.147
θ <sub>1</sub> = -0.500	.136	.167	.134	.163	.141	.171
θ <sub>2</sub> = -0.500	.159	.176	.126	.128	.141	.166
MA(2)n=50	.091	.141	.150	.091	.141	.150
θ <sub>1</sub> = 0.750	.165	.179	.134	.132	.141	.195
θ <sub>2</sub> = -0.200	.169	.182	.132	.123	.141	.215
MA(2)n=50	.102	.141	.142	.102	.141	.142
θ <sub>1</sub> = 0.750	.152	.160	.136	.120	.141	.159
θ <sub>2</sub> = 0.200	.155	.165	.132	.112	.141	.175
MA(2)n=50	.112	.141	.145	.112	.141	.145
θ <sub>1</sub> = -0.750	.149	.157	.133	.112	.141	.152
θ <sub>2</sub> = 0.200	.145	.164	.129	.133	.141	.169
MA(2)n=50	.096	.141	.153	.096	.141	.153
θ <sub>1</sub> = -0.750	.160	.174	.130	.126	.141	.179
θ <sub>2</sub> = -0.200	.156	.177	.126	.121	.141	.197

**Tab. 5 - ARMA(1,1)**

Model–n–parameters	$\sigma(\hat{\rho}_k)$	$s(\hat{\rho}_k)$	$s(\hat{\rho}^*_k)$	$\sigma(\hat{\Phi}_{kk})$	$s(\hat{\Phi}_{kk})$	$s(\hat{\Phi}^*_{kk})$
ARMA(1,1) n=50	.096	.141	.155	.096	.141	.155
Φ <sub>1</sub> = .200	.164	.177	.130	.116	.141	.185
θ <sub>1</sub> = -.750	.158	.180	.126	.106	.141	.212
ARMA(1,1) n=50	.119	.141	.143	.119	.141	.143
Φ <sub>1</sub> = .200	.151	.159	.131	.131	.141	.153
θ <sub>1</sub> = -.250	.144	.162	.128	.133	.141	.156
ARMA(1,1) n=50	.134	.141	.134	.134	.141	.134
Φ <sub>1</sub> = .200	.140	.145	.134	.137	.141	.137
θ <sub>1</sub> = .250	.137	.148	.132	.138	.141	.138
ARMA(1,1) n=50	.117	.141	.137	.117	.141	.137
Φ <sub>1</sub> = .200	.146	.152	.135	.135	.141	.147
θ <sub>1</sub> = .500	.146	.156	.132	.131	.141	.152
ARMA(1,1) n=50	.106	.141	.141	.106	.141	.141
Φ <sub>1</sub> = .200	.153	.160	.135	.126	.141	.158
θ <sub>1</sub> = .750	.154	.163	.132	.118	.141	.170
ARMA(1,1) n=50	.135	.141	.134	.135	.141	.134
Φ <sub>1</sub> = -.200	.139	.144	.134	.135	.141	.136
θ <sub>1</sub> = -.250	.135	.147	.131	.139	.141	.137
ARMA(1,1) n=50	.112	.141	.142	.112	.141	.142
Φ <sub>1</sub> = -.200	.155	.163	.134	.142	.141	.163
θ <sub>1</sub> = -.250	.155	.167	.132	.131	.141	.168
ARMA(1,1) n=50	.096	.141	.148	.096	.141	.148
Φ <sub>1</sub> = -.200	.163	.175	.134	.132	.141	.186
θ <sub>1</sub> = .500	.165	.179	.132	.121	.141	.201
ARMA(1,1) n=50	.090	.141	.151	.090	.141	.151
Φ <sub>1</sub> = -.200	.168	.181	.134	.121	.141	.201
θ <sub>1</sub> = .750	.170	.185	.131	.109	.141	.229
ARMA(1,1) n=50	.115	.141	.144	.115	.141	.144
Φ <sub>1</sub> = -.200	.150	.157	.133	.116	.141	.151
θ <sub>1</sub> = -.750	.144	.162	.129	.120	.141	.162

ARMA(1,1) n=50	.123	.141	.138	.123	.141	.138
$\Phi_1 = -.200$	.143	.149	.133	.126	.141	.142
$\theta_1 = -.500$	.138	.153	.130	.133	.141	.146
ARMA(1,1) n=50	.099	.141	.155	.099	.141	.155
$\Phi_1 = .500$	.157	.182	.132	.132	.141	.204
$\theta_1 = -.250$	.164	.189	.124	.128	.141	.203
ARMA(1,1) n=50	.142	.141	.137	.142	.141	.137
$\Phi_1 = .500$	.146	.150	.133	.134	.141	.141
$\theta_1 = .250$	.138	.153	.129	.142	.141	.141
ARMA(1,1) n=50	.136	.141	.137	.136	.141	.137
$\Phi_1 = -.500$	.150	.154	.134	.143	.141	.148
$\theta_1 = -.250$	.145	.158	.132	.137	.141	.149
ARMA(1,1) n=50	.094	.141	.153	.094	.141	.153
$\Phi_1 = -.500$	.164	.188	.135	.141	.141	.227
$\theta_1 = .250$	.175	.198	.130	.126	.141	.231
ARMA(1,1) n=50	.082	.141	.157	.082	.141	.157
$\Phi_1 = -.500$	.166	.197	.135	.127	.141	.262
$\theta_1 = .500$	.183	.208	.129	.117	.141	.284
ARMA(1,1) n=50	.103	.141	.151	.103	.141	.151
$\Phi_1 = .200$	.159	.171	.130	.124	.141	.172
$\theta_1 = -.500$	.153	.174	.126	.120	.141	.185
ARMA(1,1) n=50	.084	.141	.160	.084	.141	.160
$\Phi_1 = .500$	.158	.192	.132	.123	.141	.235
$\theta_1 = -.500$	.171	.200	.123	.116	.141	.251
ARMA(1,1) n=50	.126	.141	.136	.126	.141	.136
$\Phi_1 = -.500$	.137	.146	.135	.123	.141	.140
$\theta_1 = -.750$	.139	.152	.131	.133	.141	.143
ARMA(1,1) n=50	.121	.141	.136	.121	.141	.136
$\Phi_1 = .500$	.140	.148	.135	.131	.141	.143
$\theta_1 = .750$	.143	.153	.132	.128	.141	.147
ARMA(1,1) n=50	.078	.141	.158	.078	.141	.158
$\Phi_1 = .750$	.145	.206	.136	.131	.141	.322
$\theta_1 = -.250$	.177	.227	.124	.128	.141	.313
ARMA(1,1) n=50	.136	.141	.146	.136	.141	.146
$\Phi_1 = .750$	.158	.173	.134	.132	.141	.186
$\theta_1 = .250$	.162	.185	.127	.143	.141	.178
ARMA(1,1) n=50	.153	.141	.137	.153	.141	.137
$\Phi_1 = .750$	.154	.151	.133	.136	.141	.145
$\theta_1 = .500$	.146	.156	.129	.145	.141	.143
ARMA(1,1) n=50	.128	.141	.148	.128	.141	.148
$\Phi_1 = -.750$	.169	.181	.136	.171	.198	.132
$\theta_1 = -.250$	.171	.198	.132	.129	.141	.208

Tab. 6 – WHITE NOISE

White Noise – n parameters	$\sigma(\hat{\rho}_k)$	$s(\hat{\rho}_k)$	$s(\hat{\rho}^*_k)$	$\sigma(\hat{\Phi}_{kk})$	$s(\hat{\Phi}_{kk})$	$s(\hat{\Phi}^*_{kk})$
n=50	.136	.141	.134	.136	.141	.134
$\sigma^2_a = .100$	.140	.144	.134	.136	.141	.137
	.136	.147	.132	.139	.141	.137